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APPLICATION NO.	FILING DATE	FIRST NAMED INVENTOR	ATTORNEY DOCKET NO.	CONFIRMATION NO.
10/724,787	12/01/2003	Gianluca Paladini	2002P19673 US01	1913
7590 03/30/2010 Siemens Corporation Intellectual Property Department			EXAMINER	
			RICHER, AARON M	
170 Wood Avenue South Iselin, NJ 08830			ART UNIT	PAPER NUMBER
			MAIL DATE	DELIVERY MODE
			03/30/2010	PAPER

Please find below and/or attached an Office communication concerning this application or proceeding.

The time period for reply, if any, is set in the attached communication.

	Application No.	Applicant(s)		
	10/724,787	PALADINI, GIANLUCA		
Office Action Summary	Examiner	Art Unit		
	AARON M. RICHER	2628		
The MAILING DATE of this communication ap Period for Reply	pears on the cover sheet with the	correspondence address		
A SHORTENED STATUTORY PERIOD FOR REPL WHICHEVER IS LONGER, FROM THE MAILING D. - Extensions of time may be available under the provisions of 37 CFR 1. after SIX (6) MONTHS from the mailing date of this communication. - If NO period for reply is specified above, the maximum statutory period. - Failure to reply within the set or extended period for reply will, by statut Any reply received by the Office later than three months after the mailine earned patent term adjustment. See 37 CFR 1.704(b).	DATE OF THIS COMMUNICATIO 136(a). In no event, however, may a reply be tin will apply and will expire SIX (6) MONTHS from the, cause the application to become ABANDONE	N. mely filed the mailing date of this communication. ED (35 U.S.C. § 133).		
Status				
Responsive to communication(s) filed on 29 L This action is FINAL . 2b) ☑ Thi Since this application is in condition for allowatelessed in accordance with the practice under	s action is non-final. ance except for formal matters, pr			
Disposition of Claims				
4) Claim(s) 1-15 and 17-29 is/are pending in the 4a) Of the above claim(s) is/are withdra 5) Claim(s) 10 and 23 is/are allowed. 6) Claim(s) 1-7,9,11-15,17-20,22 and 24-29 is/are 7) Claim(s) 8 and 21 is/are objected to. 8) Claim(s) are subject to restriction and/o	re rejected.			
Application Papers				
9) The specification is objected to by the Examination 10) The drawing(s) filed on is/are: a) acceptable and applicant may not request that any objection to the Replacement drawing sheet(s) including the correct should be contacted to by the Examination.	cepted or b) objected to by the drawing(s) be held in abeyance. Section is required if the drawing(s) is ob	e 37 CFR 1.85(a). ojected to. See 37 CFR 1.121(d).		
Priority under 35 U.S.C. § 119				
 12) Acknowledgment is made of a claim for foreign priority under 35 U.S.C. § 119(a)-(d) or (f). a) All b) Some * c) None of: 1. Certified copies of the priority documents have been received. 2. Certified copies of the priority documents have been received in Application No. 3. Copies of the certified copies of the priority documents have been received in this National Stage application from the International Bureau (PCT Rule 17.2(a)). * See the attached detailed Office action for a list of the certified copies not received. 				
Attachment(s) 1) ☑ Notice of References Cited (PTO-892)	4) Interview Summary			
Notice of Draftsperson's Patent Drawing Review (PTO-948) Information Disclosure Statement(s) (PTO/SB/08) Paper No(s)/Mail Date	Paper No(s)/Mail D 5) Notice of Informal F 6) Other:			

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DETAILED ACTION

Response to Arguments

- 1. Applicant's arguments filed December 29, 2009 have been fully considered but they are not persuasive.
- 2. Applicant argues, with respect to claim 2, that Zar does not disclose interpolation in polar coordinates. However, this is not what claim 2 requires. Claim 2 requires the processor to bilinearly interpolate from LUT values using fractional offsets of the Cartesian coordinates. The Zar reference states, on page 1, that interpolation is done using a distance from some point I. As can be seen on figure 1, I is the center of the Cartesian point and the fractional distance between I and sample points is used for bilinear interpolation.
- 3. Applicant argues, with respect to claim 12, that Halmann does not suggest a format for the LUT. While Halmann is no longer used in this rejection, the Smith and Park references replacing Halmann also lack the claimed flag and integer sum. Applicant argues that the use of these particular variables is not a design choice and that the values are chosen to allow table based identification of data rather than scan conversion. However, examiner reiterates that nothing about the particular use of a Boolean flag or integer sum has been identified as critical to table based identification. If applicant replaced the Boolean flag or integer sum with floating point or fixed point variables, the invention would appear to work just as well. The use of a particular variable type to represent a particular number is a matter of design choice based on a programmer's preference.

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4. Applicant's arguments with respect to claims 1-7, 9, 11-15, 17-20, 22, and 23-27 have been considered but are moot in view of the new ground(s) of rejection.

Claim Rejections - 35 USC § 103

- 5. The following is a quotation of 35 U.S.C. 103(a) which forms the basis for all obviousness rejections set forth in this Office action:
 - (a) A patent may not be obtained though the invention is not identically disclosed or described as set forth in section 102 of this title, if the differences between the subject matter sought to be patented and the prior art are such that the subject matter as a whole would have been obvious at the time the invention was made to a person having ordinary skill in the art to which said subject matter pertains. Patentability shall not be negatived by the manner in which the invention was made.
- 6. Claims 1, 3-6, 11-15, 17-19, 25, and 27-29 are rejected under 35 U.S.C. 103(a) as being unpatentable over Smith (U.S. Patent 6,241,675) in view of Park (U.S. Patent 6,192,164)
- 7. As to claim 1, Smith discloses a system for scan converting ultrasound data from an acquisition format comprising a polar format to a two-dimensional display format comprising a Cartesian format, the system comprising:

a function having values corresponding to a spatial conversion from Cartesian coordinates of the Cartesian format the to polar coordinates of the polar format (col. 21, lines 3-11; VLSI circuitry is used to convert Cartesian raster points to polar format);

and a processor configured to identify acquired ultrasound data corresponding to the polar coordinates as a function of the values (col. 19, lines 51-66; ultrasound data is stored with respect to polar coordinates; col. 20, lines 1-42; this data is looked up using the polar coordinates converted from Cartesian),

the polar coordinates identified as a function of the values using the function for the spatial conversion from the Cartesian coordinates associated with a virtual volume free of voxel data (col. 20, line 56-col. 21, line 11; the Cartesian points are converted to polar; it is noted that since all of the actual ultrasound data is stored with respect to polar coordinates, the volume of Cartesian coordinates is not associated with the voxel data)

the processor operable to interpolate, in the polar format, from the identified acquired ultrasound data (col. 20, lines 1-42; the data is interpolated in the polar format and finally aligned to an x,y,z coordinate so it can be rasterized),

the interpolation being a function of three-dimensional rendering rays cast through the virtual volume (col. 20, line 56-col. 21, line 11; the interpolation is based on ray tracing in a Cartesian volume, the Cartesian points being converted to polar and then supplied to a filter for processing),

wherein the processor is configured to avoid scan conversion from the polar coordinates of volume data that does not contribute to a final volume rendered image by scan converting only visible voxels based on the rendering rays through the virtual volume and corresponding Cartesian coordinates (col. 20, line 56-col. 21, line 11; the scan conversion takes place using rays traced from raster points),

the identifying corresponding to identifying Cartesian coordinates associated with visible voxels of the final volume rendered image (col. 20, lines 35-46; the output data is rasterized points in a Cartesian grid; only data for the actual rasterized points is discussed as being processed).

Smith discusses lookup tables but does not expressly disclose a lookup table having values corresponding to a spatial conversion from Cartesian coordinates of the

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Cartesian format the to polar coordinates of the polar format. One example of a reference that achieves Cartesian-to-polar coordinate transformation through a lookup table is Park. Park discusses a lookup table for going from Cartesian coordinates to polar in an ultrasound system, with motivation being that it increases speed without raising cost of the overall system (col. 3, lines 42-60). It would have been obvious to one skilled in the art to modify Smith to use a lookup table for Cartesian-to-polar coordinate transformation in order to increase speed without increasing cost as taught by Park.

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- 8. As to claim 3, Park discloses a system wherein the processor is operable to determine display coordinates of interest and identify the acquired ultrasound data by inputting the display coordinates of interest into the look-up table (col. 3, lines 42-60; col. 5, lines 32-58; ultrasound data is identified by inputting x,y display coordinates; since "coordinates of interest" is not further defined by the claim, any coordinates could read on these).
- 9. As to claim 4, Smith discloses a system wherein the acquired ultrasound data represents a scan volume in the acquisition format, wherein the processor is operable to determine display coordinates for a plane through the volume as the display coordinates of interest (col. 26, lines 23-30; any slice through the plane can be specified);

further comprising a system comprising a display operable to display a twodimensional image representing the plane in the display format with the interpolated values (col. 4, lines 46-53; the portion of the volume is displayed). 10. As to claim 5, Smith discloses a system wherein the acquired ultrasound data represents a scan volume in the acquisition format (col. 19, lines 52-67), wherein the processor is operable to determine display coordinates for the rays through the volume as the display coordinates of interest (col. 20, line 56-col. 21, line 11; the rays traced through the volume are used to produce the raster lines);

further comprising a display operable to display a two-dimensional image of a Volume Rendering of at least a portion of the scan volume in the display format with the display values (col. 4, lines 46-53; the portion of the volume is displayed).

- 11. As to claim 6, Smith discloses a system wherein each of the display values is a function of an alpha blending of a plurality of acquired ultrasound data values (col. 20, lines 1-20; inherently the cubic interpolation of values reads on an alpha blending; the interpolation coefficients can be seen as the alpha values) and wherein the processor is operable to limit a number of acquired ultrasound data values blended as a function of a threshold such that scan conversion of other acquired ultrasound data values is avoided (col. 20, lines 1-20; various thresholds of data values for interpolation are disclosed, including 2 and 4).
- 12. As to claim 11, Smith discloses a system wherein the processor comprises a GPU (fig. 2, element 235; a scan converter is employed to rasterize data, thus reading on a graphics processing unit).
- 13. As to claim 12, neither Smith nor Park discloses a system wherein the look-up table values each comprise a set of two fixed-point values, one Boolean Flag, and one Integer Sum, the two fixed-point values being Polar coordinates. These, however, are

all arbitrary classes of variables and there is no disclosed criticality to them in applicant's specification. The choosing of these particular classes of variables appears to be a matter of design choice. One skilled in the art would expect the inventions of Smith and Park to work equally well with various other types of variables, such as integers, floating point variables, etc.

- 14. As to claim 13, Smith discloses setting clipping values and alpha values for blending when a set corresponds to a location outside a scanned region (col. 20, lines 23-35), but does not expressly disclose a system wherein a Boolean Flag indicates whether the set corresponds to a location outside of a scanned region. However, Official Notice has been taken of the fact that setting a flag for when data is in or out of a range is well-known in the art (see MPEP 2144.03). It would have been obvious to one skilled in the art to modify Smith and Park to set a variable when data is out of range in order to communicate this error to other parts of a computing system.
- 15. As to claim 14, see the rejection to claim 1.
- 16. As to claim 15, see the rejection to claim 1, in particular the parts dealing with the Park reference.
- 17. As to claim 17, see the rejection to claim 4. It is noted that the images generated would read on multi-planar reconstructions or MPR images since they are images comprising data from various planes of a volume.
- 18. As to claim 18, see the rejection to claim 5.
- 19. As to claim 19, see the rejection to claim 6.
- 20. As to claim 25, see the rejection to claim 13.

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21. As to claim 27, Smith discloses a method further comprising: (d) Volume Rendering as a function of the display values as a function of time (col. 1, line 59-col. 2, line 18; various time-based views, such as a motion mode showing displacement over time, can be selected).

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- 22. As to claim 28, see the rejection to claim 1. Claim 28 additionally recites that conversion from polar coordinates occurs without separate scan conversion and then rendering, which is also disclosed by Smith (col. 19, line 52-col. 21, line 11; the scan conversion and rendering happens in the same step; display values are directly determined using the x,y,z coordinates, rather than converting polar to Cartesian and *then* determining which values are actually displayed). Claim 28 further recites that scan conversion of different ultrasound values occurs for different observer locations, which is also disclosed by Smith (col. 26, lines 36-48; after one "viewport" has been rendered, a table is checked to see if others need to be rendered using different ultrasound values)
- 23. As to claim 29, see the rejection to claim 1.
- 24. Claim 2 is rejected under 35 U.S.C. 103(a) as being unpatentable over Smith in view of Park and further in view of Zar ("A Scan Conversion Engine for Standard B-Mode Ultrasonic Imaging").
- 25. As to claim 2, Park discloses values comprising polar coordinates and lookup table entries indexed by Cartesian coordinates, as noted in the rejection to claim 1, but does not expressly disclose a processor operable to bilinearly interpolate from the lookup table values using fractional offsets of Cartesian coordinates. Zar, however,

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discloses a bilinear interpolation using fraction offsets of Cartesian coordinates (p. 1, Introduction) to be able to convert to polar using a lookup table (p. 2, LUTs and Constant LUTs sections). The motivation for using this system is to accomplish scan conversion at a very low cost (p. 1, Abstract). It would have been obvious to one skilled in the art to modify Smith and Park to use bilinear interpolation and LUTs to convert

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26. Claims 7 and 20 are rejected under 35 U.S.C. 103(a) as being unpatentable over Smith in view of Park and further in view of Drebin (U.S. Patent 4,835,712).

polar to Cartesian coordinates in order to reduce cost as taught by Zar.

- 27. As to claim 7, neither Smith nor Park discloses a system comprising an RGBA look-up table addressed by the display values, the RGBA look-up table operable to output an RGBA value corresponding to the display value. Drebin, however, discloses a system that inputs monochrome display values to a lookup table and outputs RGBA values for those values (col. 7, lines 44-62). The motivation for this is to simulate an image illuminated by one or more sources of light (col. 2, lines 4-24). It would have been obvious to one skilled in the art to modify Smith and Park to use a lookup table to convert between display values and RGBA values in order to simulate an image illuminated by one or more sources of light as taught by Drebin.
- 28. As to claim 20, see the rejection to claim 7.
- 29. Claims 9 and 22 are rejected under 35 U.S.C. 103(a) as being unpatentable over Smith in view of Park and further in view of Swerdloff (U.S. Patent 5,483,567).
- 30. As to claim 9, neither Smith nor Park discloses a system wherein the look-up table values correspond to the spatial conversion from the display format to the

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acquisition format for at least one acquisition plane; further comprising an additional look-up table corresponding to spatial conversion from the display format to the acquisition format across multiple acquisition planes. Swerdloff, however, discloses a system wherein a change in relationship between polar and Cartesian voxels, such as a change when changing an acquisition plane, necessitates creation of another lookup table (col. 9, lines 6-25). This is motivated by the fact that the current lookup table will no longer be accurate (col. 9, lines 19-25). It would have been obvious to one skilled in the art to modify Smith and Park to use an additional lookup table when multiple acquisition planes are used in order to have an accurate lookup table as taught by Swerdloff.

- 31. As to claim 22, see the rejection to claim 9.
- 32. Claims 24 and 26 are rejected under 35 U.S.C. 103(a) as being unpatentable over Smith in view of Park and further in view of Halmann (U.S. Patent 6,526,163).
- 33. As to claim 24, neither Smith nor Park discloses generating the look-up table as a function of a spatial relationship of a display format with user configured acquisition parameters. Halmann, however, does disclose such a limitation (col. 7, lines 54-59; tables generated are dependent on a selected mode of operation; col. 3, lines 59-62 states that this mode is determined by a user and col. 5, line 51-58 states that the mode determines acquisition parameters). While not expressly disclosed by the reference, a common motivation for pre-calculating conversion tables is to speed up a system when image acquisition begins. Calculating only the necessary tables, as Halmann does would further speed setup times. It would have been obvious to one skilled in the art to

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modify Smith and Park to pre-calculate only necessary conversion tables to achieve greater efficiency as taught by Halmann.

34. As to claim 26, Park discloses a system wherein (d) comprises generating a two-dimensional look-up table with acquisition format coordinates for each coordinate of a Cartesian volume (col. 3, lines 43-65; a LUT with theta and radius values is calculated for each x,y coordinate).

Conclusion

- 35. Claims 10 and 23 are allowed.
- 36. Claims 8 and 21 are objected to as being dependent upon a rejected base claim, but would be allowable if rewritten in independent form including all of the limitations of the base claim and any intervening claims.

Any inquiry concerning this communication or earlier communications from the examiner should be directed to AARON M. RICHER whose telephone number is (571)272-7790. The examiner can normally be reached on weekdays from 8:30AM-5:00PM.

If attempts to reach the examiner by telephone are unsuccessful, the examiner's supervisor, Kee Tung can be reached on (571) 272-7794. The fax phone number for the organization where this application or proceeding is assigned is 571-273-8300.

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/Aaron M Richer/
Primary Examiner, Art Unit 2628 3/27/10